

# Curriculum Vitae

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Visual Intelligence Laboratory  
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### Education

- Ph.D. in Electrical Engineering, KAIST, Korea Feb. 2006
- M.S. in Electrical Engineering, KAIST, Korea Feb. 2000
- B.S. in Electrical Engineering, KAIST, Korea Feb. 1998

### Work Experiences

- **Associate Professor** Feb. 2018 – present  
Department of Mechanical Engineering, KAIST, Korea,
- **Assistant/Associate Professor** Aug. 2008 – Feb. 2018  
School of Electrical Engineering and Computer Science, GIST, Korea,
- **Technical Adviser** April. 2017 – Dec. 2017  
Samsung Electronics (Visual Display Division)
- **Steering Committee Member** Mar. 2017 – Present  
National Strategic Projects on VR/AR
- **Technical Adviser** Mar. 2017 – Aug. 2017  
NAVER Labs (Mobility Team)
- **Steering Committee Member** Dec. 2015 – Feb. 2018  
Korea Culture Technology Institute
- **Visiting Scholar** Sept. 2013 – Aug. 2014  
Korea Institute of Science and Technology (KIST)
- **Post-doctoral Fellow**, Aug. 2006 – Aug. 2008  
Perception Team, INRIA Rhône-Alpes, France,
- **Post-doctoral Researcher** March 2006 – May 2006  
Robotics and Computer Vision Lab., KAIST, Korea

### Research Interests

- Computer vision, machine learning, pattern recognition, especially including
  - Event camera- and 360° camera-based vision
  - Vision-based ADAS for autonomous driving
  - 3D reconstruction from images (two-/multi-view stereo, structure-from-motion, SLAM)
  - Multi-target detection and tracking
  - Visual odometry, optical flow estimation
  - 3D object detection and recognition
  - Multi-sensor fusion

## Publications (International)

### SCI Journal

49. Yeon Kun Lee\*, Jaeseok Jeong\*, Jong Seob Yun\*, Won June Cho\*, and **Kuk-Jin Yoon** (\*: equal contribution), “SpherePHD: Applying CNNs on a Spherical PolyHeDron Representation of 360° Images,” under major revision, IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI), 2020. (IF: 17.73, rank: 1/265, 1/133)
48. S. Mohammad Mostafavi I., Lin Wang, and **Kuk-Jin Yoon**, “Learning to Reconstruct HDR Images from Events, with Applications to Depth and Flow,” major revision submitted, International Journal of Computer Vision (IJCV), 2020. (IF: 6.071, rank: 13/133)
47. Lin Wang, Wonjune Cho, and **Kuk-Jin Yoon**, “Deceiving Image-to-Image Translation Networks for Autonomous Driving with Adversarial Perturbations,” IEEE Robotics and Automation Letters (RA-L), accepted, 2020.
46. Jeong-Kyun and **Kuk-Jin Yoon**, “Joint Estimation of Camera Orientation and Vanishing Points from Lines,” International Journal of Computer Vision (IJCV), accepted, 2019. (IF: 6.071, rank: 13/133)
45. Yeong-Jun Cho and **Kuk-Jin Yoon**, “Distance-based Camera Network Topology Inference for Person Re-identification,” Pattern Recognition Letters, accepted, 2019. (IF: 2,810, rank: 50/133)
44. Chang-Ryeol Lee and **Kuk-Jin Yoon**, “Confidence Analysis of Feature Points for Visual-Inertial Odometry of Urban Vehicles,” IET Intelligent Transport Systems, in press, 2019. (IF: 2.050, rank: 19/37)
43. Min-Gyu Park and **Kuk-Jin Yoon**, “As-Planar-As-Possible Depth Map Estimation,” Computer Vision and Image Understanding (CVIU), in press, 2019. (IF: 2.645, rank: 58/133)
42. Yeong-Jun Cho, Su-A Kim, Jae-Han Park, Kyuewang Lee, and **Kuk-Jin Yoon**, “Joint Person Re-identification and Camera Network Topology Inference in Multiple Cameras,” Computer Vision and Image Understanding (CVIU), in press, 2019. (IF: 2.645, rank: 58/133)
41. Hanmu Park and **Kuk-Jin Yoon**, “Exploiting Multi-layer Graph Factorization for Multi-attributed Graph Matching,” Pattern Recognition Letters, in press, 2019. (IF: 2.810, rank: 50/133)
40. Hanmu Park and **Kuk-Jin Yoon**, “Consistent Multiple Graph Matching with Multi-layer Random Walks Synchronization,” Pattern Recognition Letters, in press, 2019. (IF: 2.810, rank: 50/133)
39. Min-Gyu Park and **Kuk-Jin Yoon**, “Learning and Selecting Confidence Measures for Robust Stereo Matching,” IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI), vol. 41, no. 6, pp. 1397-1411, 2019. (IF: 17.73, rank: 1/265, 1/133)
38. Ju Hong Yoon, Chang-Ryeol Lee, Ming-Hsuan Yang, and **Kuk-Jin Yoon**, “Structural Constraint Data Association for Online Multi-Object Tracking,” International Journal of Computer Vision (IJCV), vol. 127, no. 1, pp. 1-21, 2019. (IF: 6.071, rank: 13/133)

37. Chang-Ryeol Lee, Ju Hong Yoon, and **Kuk-Jin Yoon**, “Calibration and Noise Identification of a Rolling Shutter Camera and a Low-cost Inertial Measurement Unit,” *Sensors*, vol. 18, no. 7, 2018. (IF: 2.475, rank: 16/61)
36. Yeong-Jun Cho and **Kuk-Jin Yoon**, “PAMM: Person Re-identification via Pose-aware Multi-shot Matching,” *IEEE Transactions on Image Processing (TIP)*, vol. 27, no. 8, pp. 3739-3752, 2018. (IF: 5.071, rank: 11/132, 24/260)
35. Jeong-Kyun Lee and **Kuk-Jin Yoon**, “Temporally Consistent Road Surface Profile Estimation Using Stereo Vision,” *IEEE Transactions on Intelligent Transportation System (T-ITS)*, vol. 19, no. 5, pp. 1618-1628, 2018. (IF: 4.051, rank: 5/128)
34. Han-Mu Park and **Kuk-Jin Yoon**, “Multi-attributed Graph Matching with Multi-layer Graph Structure and Multi-layer Random Walks,” *IEEE Transactions on Image Processing (TIP)*, vol. 27, no. 5, pp. 2314-2325, 2018. (IF: 5.071, rank: 11/132, 24/260)
33. Seung Hwan Bae and **Kuk-Jin Yoon**, “Confidence-Based Data Association and Discriminative Deep Appearance Learning for Robust Online Multi-Object Tracking,” *IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)*, vol. 40, no. 3, pp. 595-610, 2018. (IF: 9.455, rank: 3/260, 2/132)
32. Han-Mu Park, Dae-Yong Cho, and **Kuk-Jin Yoon**, “Greedy Refinement of Object Proposals via Boundary-aligned Minimum Bounding Box Search,” *IET Computer Vision (CVI)*, vol. 12, no. 3, pp. 357-363, 2018. (IF: 1.087, rank: 94/132)
31. Han-Mu Park, Se-Hoon Park, and **Kuk-Jin Yoon**, “Multi-object Tracking via Tracklet Confidence-Aided Relative Motion Analysis,” *SPIE Journal of Electronic Imaging*, 2017.
30. Hohyun Cho, Min-Koo Kang, Sangtae Ahn, Moonyoung Kwon, **Kuk-Jin Yoon**, Kiwoong Kim, and Sung Chan Jun, “Cognitive Response and Cortical Oscillatory Processing for Various Stereoscopic Depths - Simultaneous EEG/MEG Study,” *Journal of Integrative Neuroscience*, 2017.
29. Min-Koo Kang, Hohyun Cho, Han-Mu Park, Sung Chan Jun, and **Kuk-Jin Yoon**, “A Wellness Platform for Stereoscopic 3D Video Systems Using EEG-based Visual Discomfort Evaluation Technology,” *Applied Ergonomics*, vol. 62, pp. 158-167, 2017.
28. Yeong-Jun Cho, Seung Hwan Bae, and **Kuk-Jin Yoon**, “Multi-Classier-based Automatic Polyp Detection in Endoscopic Images,” *Journal of Medical and Biological Engineering*, Published Online, Nov. 28, 2016.
27. Hohyun Cho, Min-Koo Kang, Sangtae Ahn, Moonyoung Kwon, **Kuk-Jin Yoon**, Kiwoong Kim, and Sung Chan Jun, “Cortical Responses and Shape Complexity of Stereoscopic Image – A Simultaneous EEG/MEG Study,” *NeuroSignals*, vol. 24, no. 1, pp. 102–112, Oct. 24, 2016.
26. Seung Hwan Bae, Jong-Youl Park, and **Kuk-Jin Yoon**, “Joint Estimation of Multi-Target SNR and Dynamic States in Cluttered Environment,” *IET Radar, Sonar and Navigation*, Published Online, Oct. 19, 2016.

25. Han-Mu Park and **Kuk-Jin Yoon**, “Encouraging Second-order Consistency for Multiple Graph Matching,” *Machine Vision and Applications*, vol. 27, no. 7, pp. 1021–1034, Oct. 1, 2016.
24. Yongho Shin and **Kuk-Jin Yoon**, “PatchMatch Belief Propagation Meets Depth Upsampling for High-resolution Depth Maps,” *Electronics Letters*, vol. 52, no. 17, pp. 1445–1447, Aug. 18, 2016.
23. Ju Hong Yoon, Ming-Hsuan Yang, and **Kuk-Jin Yoon**, “Interacting Multiview Trackers,” *IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)*, vol. 38, no. 5, pp. 903–917, May 1, 2016.
22. Yongho Shin and **Kuk-Jin Yoon**, “Robust Spatiotemporal Stereo against Image Motion and Temporal Disparity Variation,” *Electronics Letters*, vol. 52, no. 7, pp. 515–517, Mar. 31, 2016.
21. Seung Hwan Bae and **Kuk-Jin Yoon**, “Polyp Detection via Imbalanced Learning and Discriminative Feature Learning,” *IEEE Transactions on Medical Imaging (TMI)*, vol. 34, no. 11, pp. 2379–2393, Nov. 18, 2015.
20. Jungho Kim, **Kuk-Jin Yoon**, and In So Kweon, “Bayesian Filtering for Keyframe-based Visual SLAM,” *International Journal of Robotics Research (IJRR)*, vol. 34, no. 4-5, pp. 517–531, April 15, 2015.
19. Jonghee Park and **Kuk-Jin Yoon**, “Real-time Line Matching from Stereo Images using a Non-parametric Transform of Spatial Relations and Texture Information,” *SPIE Optical Engineering*, vol. 54, no. 2, pp. 023106(1–11), Feb. 19, 2015.
18. Min-Gyu Park, Jonghee Park, Yongho Shin, Eul-Gyoon Lim, and **Kuk-Jin Yoon**, “Stereo Vision with Image-guided Structured-light Pattern Matching,” *IET Electronics Letters*, vol. 51, no. 3, pp. 238–239, Feb. 05, 2015.
17. Jong-Hee Park, Ju Hong Yoon, Min-Gyu Park, and **Kuk-Jin Yoon**, “Dynamic Point Clustering with Line Constraints for Moving Object Detection in DAS,” *IEEE Signal Processing Letters (SPL)*, vol. 21, no. 10, pp.1255–1259, Jun. 24, 2014.
16. Minkoo Kang and **Kuk-Jin Yoon**, “Depth-Discrepancy-Compensated Inter-Prediction with Adaptive Segment Management for Multiview Depth Video Coding,” *IEEE Transactions on Multimedia(TMM)*, vol. 16, no. 6, pp. 1563–1573, May 14, 2014.
15. Seung Hwan Bae and **Kuk-Jin Yoon**, “Robust Online Multi-Object Tracking with Data Association and Track Management,” *IEEE Transactions on Image Processing (TIP)*, vol. 23, no. 7, pp. 2820–2833, April 29, 2014.
14. Min-Koo Kang, Daeyoung Kim, and **Kuk-Jin Yoon**, “Adaptive Support of Spatial-Temporal Neighboring Samples for Depth Map Sequence Up-sampling,” *IEEE Signal Processing Letters (SPL)*, vol. 21, no. 2, pp.150–154, Feb. 2014.
13. Ju Hong Yoon, Du Yong Kim, and **Kuk-Jin Yoon**, “Gaussian Mixture Importance Sampling Function for Unscented SMC-PHD Filter,” *Signal Processing*, vol. 93, no. 9, pp. 2664–2670, Sep. 1, 2013.

12. Jae-changean Jeong, Ho-chul Shin, Jiho Chang, Eul-gyun Lim, Seungmin Choi, **Kuk-Jin Yoon**, and Jae-il Cho, “High-quality Stereo Depth Map Generation Using Infrared Pattern Projection,” *ETRI Journal*, vol. 35, no. 6, pp. 1011–1019, June 1, 2013.
11. Seung Hwan Bae, Du Yong Kim, Ju Hong Yoon, Vladimir Shin, and **Kuk-Jin Yoon**, “Automated Multi-target Tracking with Kinematic and Non-kinematic Information,” *IET Radar, Sonar and Navigation*, vol. 6, no. 4, pp. 272–281, April 05, 2012.
10. **Kuk-Jin Yoon**, “Stereo Matching based on Non-linear Diffusion with Disparity-Dependent Support-Weights”, *IET Computer Vision*, vol. 6, no. 4, pp. 306–313, Sep. 13, 2012.
9. Ju Hong Yoon, Du Yong Kim, and **Kuk-Jin Yoon**, “Efficient Importance Sampling Function Design for Sequential Monte Carlo PHD Filter”, *Signal Processing*, vol. 92, no. 9, pp. 2315–2321, Sep. 1, 2012.
8. Min-Gyu Park and **Kuk-Jin Yoon**, “Optimal Key-frame Selection for Video-based Structure-from-motion”, *Electronics Letters (EL)*, vol. 47, no. 25, pp. 1367–1369, Dec. 15, 2011.
7. **Kuk-Jin Yoon** and Sung-Kee Park, “Improving Stereo Matching with Symmetric Cost Functions”, *IEICE Electronics Express*, vol. 8, no. 2, pp.57–63, 2011.
6. **Kuk-Jin Yoon**, Emmanuel Prados, and Peter Sturm, “Joint Estimation of Shape and Reflectance using Multiple Images with Known Illumination Conditions”, *International Journal of Computer Vision (IJCV)*, vol. 86, no. 2-3, pp. 192–210, 2010.
5. Ji-Ho Cho, **Kuk-Jin Yoon**, and K. H. Lee, “Alpha-matte-based Depth Map Enhancement for Hairy Objects,” *Electronics Letters*, vol. 46, no. 3, pp. 211–213, 2010.
4. **Kuk-Jin Yoon** and In So Kweon, “Distinctive Similarity Measure for Stereo Matching Under Point Ambiguity,” *Computer Vision and Image Understanding (CVIU)*, vol. 112, no. 2, pp. 173–183, 2008.
3. Sungho Kim, **Kuk-Jin Yoon**, and In So Kweon, “Object Recognition Using a Generalized Robust Invariant Feature and Gestalt’s Law of Proximity and Similarity”, *Pattern Recognition (PR)*, vol. 41, no. 2, pp. 726–741, 2008.
2. **Kuk-Jin Yoon** and In So Kweon, “Adaptive Support-Weight Approach for Correspondence Search,” *IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)*, vol. 28, no. 4, pp. 650–656, 2006.
1. **Kuk-Jin Yoon** and In So Kweon, “Voting-based Separation of Diffuse and Specular Pixels,” *Electronics Letters*, vol. 40, no. 20, pp. 1260–1261, 2004.

## Conference

63. Lin Wang, Tae-Kyun Kim, and **Kuk-Jin Yoon**, “EventSR: From Asynchronous Events to Image Reconstruction, Restoration, and Super-Resolution via End-to-End Adversarial Learning,” *IEEE International Conference on Computer Vision and Pattern Recognition (CVPR)*, 2020.

62. S. Mohammad Mostafavi I., Jonghyun Choi, and **Kuk-Jin Yoon**, “Learning to Super Resolve Intensity Images from Events,” IEEE International Conference on Computer Vision and Pattern Recognition (CVPR), 2020.
61. Lin Wang, Wonjune Cho, and **Kuk-Jin Yoon**, “Deceiving Image-to-Image Translation Networks for Autonomous Driving with Adversarial Perturbations,” International Conference on Robotics and Automation(ICRA), 2020.
60. Pranjay Shyam, Kuk-Jin Yoon, and Kyung-Soo Kim, “Dynamic Anchor Selection for Improving Object Localization,” International Conference on Robotics and Automation(ICRA), 2020.
59. Ju Hong Yoon, Min-Gyu Park, Youngbae Hwang, and Kuk-Jin Yoon, “Learning Depth from Endoscopic Images,” International Conference on 3D Vision (3DV), 2019.
58. Yeon Kun Lee\*, Jaeseok Jeong\*, Jong Seob Yun\*, Won June Cho\*, and **Kuk-Jin Yoon** (\*: equal contribution), “SpherePHD: Applying CNNs on a Spherical PolyHeDron Representation of 360° Images,” IEEE International Conference on Computer Vision and Pattern Recognition (CVPR), 2019.
57. Lin Wang\*, S. Mohammad Mostafavi I.\*, and **Kuk-Jin Yoon** (\*: equal contribution), “Event-based High Dynamic Range Image and Very High Frame Rate Video Generation using Conditional Generative Adversarial Networks,” IEEE International Conference on Computer Vision and Pattern Recognition (CVPR), 2019.
56. Jeong-Yun Na and **Kuk-Jin Yoon**, “Stereo Vision aided Image Dehazing using Deep Neural Network,” ACM MULTIMEDIA 2018 Workshop and Challenge on Comprehensive Video Understanding in the Wild (ACM MM - CoVieW’18), 2018.
55. Young-Chul Yoon and **Kuk-Jin Yoon**, “Animal Detection in Huge Air-view Images using CNN-based Sliding Window,” International Workshop on Frontiers of Computer Vision (IW-FCV), Hakodate, Japan, 2018. (Winning the best student paper award at FCV 2018)
54. Yeong-Jun Cho, Jae-Han Park, Su-A Kim, Kyuewang Lee, and **Kuk-Jin Yoon**, “Unified Framework for Automated Person Re-identification and Camera Network Topology Inference in Camera Networks,” International Workshop on Cross-domain Human Identification (in conjunction with ICCV), 2017.
53. Jeong-Kyun Lee, Jae-Won Yae, Min-Gyu Park, and **Kuk-Jin Yoon**, “Joint Layout Estimation and Global Multi-View Registration for Indoor Reconstruction,” IEEE International Conference on Computer Vision (ICCV), 2017.
52. Chang-Ryeol Lee, YeongWon Kim, Dae-Yong Cho, Yong-Hoon Kwon, Hyeok-Jae Choi, and **Kuk-Jin Yoon**, “Automatic Content-aware Projection for 360° Videos,” IEEE International Conference on Computer Vision (ICCV), 2017.
51. Min-Gyu Park, Ju Hong Yoon, Jonghee Park, Jeong-Kyun Lee, and **Kuk-Jin Yoon**, “Learning to Detect Dynamic Feature Points,” IEEE Intelligent Vehicles Symposium (IV), CA, USA, June 11-14, 2017.

50. Suho Cho and **Kuk-Jin Yoon**, “Multiple Styles Transfer Emphasizing Visual Saliency,” International Workshop on Frontiers of Computer Vision (FCV), 2017.
49. Jeong-Kyun Lee and **Kuk-Jin Yoon**, “Three-Point Direct Stereo Visual Odometry,” British Machine Vision Conference (BMVC), 2016.
48. Han-Mu Park and **Kuk-Jin Yoon**, “Multi-attributed Graph Matching with Multi-layer Random Walks,” European Conference on Computer Vision (ECCV), 2016.
47. Se-Hoon Park, Kyuewang Lee, and **Kuk-Jin Yoon**, “Robust Online Multiple Object Tracking based on the Confidence-based Relative Motion Network and Correlation Filter,” International Conference on Image Processing (ICIP), 2016.
46. Kyuewang Lee, Se-Hoon Park, and **Kuk-Jin Yoon**, “PSR-Deterministic Search Range Penalization Method on Kernelized Correlation Filter Tracker,” International Conference on Ubiquitous Robots and Ambient Intelligence (URAI), 2016.
45. Yeong-Jun Cho and **Kuk-Jin Yoon**, “Improving Person Re-identification via Pose-aware Multi-shot Matching,” IEEE International Conference on Computer Vision and Pattern Recognition (CVPR), 2016.
44. Ju Hong Yoon, Chang-Ryeol Lee, Ming-Hsuan Yang, and **Kuk-Jin Yoon**, “Hierarchical Online Multi-object Tracking via Structural Constraint Event Aggregation,” IEEE International Conference on Computer Vision and Pattern Recognition (CVPR), 2016.
43. Se-Hoon Park, Min-Gyu Park and **Kuk-Jin Yoon**, “Confidence-based Weighted Median Filter for Effective Disparity Map Refinement,” International Conference on Ubiquitous Robots and Ambient Intelligence (URAI), 2015.
42. Yongho Shin and **Kuk-Jin Yoon**, “Spatiotemporal Stereo Matching with 3D Disparity Profiles,” British Machine Vision Conference (BMVC), 2015.
41. Jeong-Kyun Lee and **Kuk-Jin Yoon**, “Real-time Joint Estimation of Camera Orientation and Vanishing Points,” IEEE International Conference on Computer Vision and Pattern Recognition (CVPR), 2015.
40. Min-Gyu Park and **Kuk-Jin Yoon**, “Leveraging Stereo Matching with Learning-based Confidence Measures,” IEEE International Conference on Computer Vision and Pattern Recognition (CVPR), 2015.
39. Ju Hong Yoon, Ming-Hsuan Yang, Jongwoo Lim, and **Kuk-Jin Yoon**, “Bayesian Multi-object Tracking Using Motion Context from Multiple Objects,” IEEE Winter Conference on Applications of Computer Vision (WACV), 2015.
38. Seung Hwan Bae and **Kuk-Jin Yoon**, “Robust Online Multi-Object Tracking based on Tracklet Confidence and Online Discriminative Appearance Learning,” IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2014.

37. Chang-Ryeol Lee, Ju Hong Yoon, and **Kuk-Jin Yoon**, “Robust Calibration of an Ultra-Low-Cost Inertial Measurement Unit and a Camera: Handling of Severe System Uncertainty,” IEEE International Conference on Robotics and Automation (ICRA), 2014.
36. Yongho Shin and **Kuk-Jin Yoon**, “Spatiotemporal Stereo Matching for Dynamic Scenes with Temporal Disparity Variation”, International Conference on Image Processing (ICIP), 2013.
35. Ju Hong Yoon, Du Yong Kim, and **Kuk-Jin Yoon**, “Multi-Object Tracking Using Hybrid Observation in PHD filter”, International Conference on Image Processing (ICIP), 2013.
34. H. Cho, M.-K. Kang, **Kuk-Jin Yoon**, and S. C. Jun, “Feasibility Study for Visual Discomfort Assessment on Stereo Images using EEG,” International Conference on 3D Imaging (IC3D), 2012.
33. Min-Gyu Park and **Kuk-Jin Yoon**, “Efficient Point Feature Tracking based on Self-aware Distance Transform,” British Machine Vision Conference (BMVC), 2012.
32. Ju Hong Yoon, Du Yong Kim, and **Kuk-Jin Yoon**, “Visual Tracking via Adaptive Tracker Selection with Multiple Features,” European Conference on Computer Vision (ECCV), 2012.
31. Dae-Young Kim and **Kuk-Jin Yoon**, “High Quality Depth Map Up-sampling with Consideration for Edge Noise of Range Sensors,” IEEE International Conference on Image Processing (ICIP), 2012 (oral presentation).
30. Ji-Ho Cho, Min Ki Park, **Kuk-Jin Yoon**, and Kwan H. Lee, “Automatic Video Matting with Temporal Coherence using Time-of-flight Sensor”, 28th Picture Coding Symposium, 2010.
29. **Kuk-Jin Yoon** and Min-Gil Shin, “Reducing Ambiguity in Object Recognition using Relational Information,” Asian Conference on Computer Vision (ACCV), pp. 293–306, 2010.
28. **Kuk-Jin Yoon**, Min-Gil Shin, and Ji-Hyo Lee, “Recognizing 3D Objects with 3D Information from Stereo Vision,” International Conference on Pattern Recognition (ICPR), pp. 4020–4023, 2010.
27. Yong-Ho Shin, Min-Gyu Park, Young-Sun Jeon, Young-Su Moon, Shi-Hwa Lee, and **Kuk-Jin Yoon**, “Tone Correction with Dynamic Objects for Seamless Image Mosaic,” Color and Reflectance in Imaging and Computer Vision Workshop 2010 (in conjunction with ECCV’2010), 2010.
26. Peter Sturm, Amaël Delaunoy, Pau Gargallo, Emmanuel Prados, **Kuk-Jin Yoon**, “3D and Appearance Modeling from Images,” 14th Iberoamerican Congress on Pattern Recognition (Invited Talk), 2009.
25. **Kuk-Jin Yoon**, Yekeun Jeong, and In So Kweon, “Support Aggregation via Non-linear Diffusion with Disparity-Dependent Support-Weights for Stereo Matching,” Asian Conference on Computer Vision (ACCV), 2009.
24. **Kuk-Jin Yoon**, Emmanuel Prados, and Peter Sturm, “Generic Scene Recovery using Multiple Images”, International Conference on Scale Space and Variational Methods in Computer Vision (SSVM), 2009.



23. Jean-Charles Bazin, **Kuk-Jin Yoon**, In So Kweon, Cedric Demonceaux, and Pascal Vasseur, “Particle Filter Approach Adapted to Catadioptric Images for Target Tracking Application,” British Machine Vision Conference (BMVC), 2009.
22. Jungho Kim, **Kuk-Jin Yoon**, and In So Kweon, “Robust 3-D Visual SLAM in a Large-scale Environment,” International Symposium on Robotics Research (ISRR) (Invited Talk), 2009.
21. Jean-Charles Bazin, Dang-Quang Pham, Inso Kweon, and **Kuk-Jin Yoon**, “Automatic Method for Closed Eye Correction,” IEEE International Conference on Image Processing (ICIP), 2009.
20. **Kuk-Jin Yoon** and In So Kweon, “Stereo Matching with the Distinctive Similarity Measure,” IEEE International Conference on Computer Vision (ICCV), 2007.
19. **Kuk-Jin Yoon**, Amaël Delaunoy, Pau Gargallo, and Peter Sturm, “Toward Global and Model based Multiview Stereo Methods for Shape and Reflectance Estimation,” Workshop on Photometric Analysis and Computer Vision (PACV) (in conjunction with ICCV), 2007.
18. **Kuk-Jin Yoon** and In So Kweon, “Stereo Matching with Symmetric Cost Functions,” IEEE Conference on Computer Vision and Pattern Recognition (CVPR), pp. 2371–2377, 2006.
17. **Kuk-Jin Yoon** and In So Kweon, “Correspondence Search in the Presence of Specular Highlights using Specular-Free Two-Band Images,” Lecture Notes in Computer Science–Asian Conference on Computer Vision (ACCV), vol. 3852, pp. 761–770, 2006.
16. **Kuk-Jin Yoon**, Yoo Jin Choi, and In So Kweon, “Fast Separation of Reflection Components Using a Specularity-Invariant Image Representation,” IEEE International Conference on Image Processing (ICIP), pp. 973–976, 2006.
15. Sungho Kim, **Kuk-Jin Yoon**, and In So Kweon, “Background Robust Object Labeling by Voting of Weight-Aggregated Local Features,” International Conference on Pattern Recognition (ICPR), pp. 219–222,, 2006.
14. Sungho Kim, **Kuk-Jin Yoon**, and In So Kweon, “Object Recognition Using a Generalized Robust Invariant Feature and Gestalt’s Law of Proximity and Similarity,” IEEE Workshop on Perceptual Organization in Computer Vision (in conjunction with CVPR), pp. 193–200, 2006.
13. **Kuk-Jin Yoon** and In So Kweon, “Locally Adaptive Support-Weight Approach for Visual Correspondence Search,” IEEE Conference on Computer Vision and Pattern Recognition (CVPR), vol. 2, pp. 924–931, 2005.
12. **Kuk-Jin Yoon**, Yoo Jin Choi, and In So Kweon, “Dichromatic-Based Color Constancy Using Dichromatic Slope and Dichromatic Line Space,” IEEE International Conference on Image Processing (ICIP), vol. 3, pp. 960–963, 2005.
11. **Kuk-Jin Yoon**, Yoo-Jin Choi, and In So Kweon, “Illuminant Chromaticity Estimation Using Dichromatic Slope and Dichromatic Line Space,” Korea-Japan Joint Workshop on Frontiers of Computer Vision (FCV), pp. 219–224, 2005.

10. **Kuk-Jin Yoon** and In So Kweon, “Human Perception Based Color Image Quantization,” International Conference on Pattern Recognition (ICPR), vol. 1, pp. 664–667, 2004.
9. Ouk Choi, **Kuk-Jin Yoon**, and In So Kweon, “A Hierarchical Window Based Approach for Correspondence Problem in Vision,” International Conference on Mechatronics and Information Technology (ICMIT), pp. 590–594, 2003.
8. **Kuk-Jin Yoon** and In So Kweon, “Color Image Segmentation Considering of Human Sensitivity for Color Pattern Variations,” SPIE Photonics Boston 2001 : Intelligent Robot and Computer Vision XX: Algorithms, Techniques and Active Vision, vol. 4572, pp. 269–278, 2001.
7. **Kuk-Jin Yoon** and In So Kweon, “Artificial Landmark Tracking Based on the Color Histogram,” IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), vol. 4, pp. 1918–1923, 2001.
6. **Kuk-Jin Yoon** and In So Kweon, “Landmark Design and Real-Time Landmark Tracking for Mobile Robot Localization,” SPIE Photonics Boston 2001 : Mobile Robots XVI, vol. 4573, pp. 219–226, 2001.
5. **Kuk-Jin Yoon**, Gi-Jeong Jang, Sung-Ho Kim, and In So Kweon, “Fast Landmark Tracking and Localization Algorithm for the Mobile Robot Self-Localization,” IFAC Workshop on Mobile Robot Technology, pp. 190–195, 2001.
4. **Kuk-Jin Yoon**, In So Kweon, Chan-Ho Lee, Jong-Kyu Oh, and In-Taek Yeo, “Landmark Design and Real-Time Landmark Tracking Using Color Histogram for Mobile Robot Localization,” International Symposium on Robotics (ISR), pp. 1083–1088, 2001.
3. Jong-Eun Ha, Jin-Young Yang, **Kuk-Jin Yoon**, and In So Kweon, “Self-Calibration Using the Linear Projective Reconstruction,” IEEE International Conference on Robotics and Automation (ICRA), vol. 1, pp. 885–890, 2000.
2. **Kuk-Jin Yoon** and In So Kweon, “Moving Object Segmentation Algorithm for Human-like Vision System,” International Workshop on Human-friendly Welfare Robotic Systems (HWRS), pp. 109–114, 2000.
1. **Kuk-Jin Yoon**, In So Kweon, Chang-Yeong Kim and Yang-Seok Seo, “Moving Object Segmentation Based on Human Visual Sensitivity,” Lecture Notes in Computer Science–Biologically Motivated Computer Vision (BMCV), vol. 1811, pp. 62–72, 2000.

## Patents

### International

6. (Pending) Kee Chang Lee, Wonhee Lee, **Kuk Jin Yoon**, Yongho Shin, Yeong Won Kim, Jin Ho Song, “Stereo Matching Method and Apparatus”, Patent Pending, US20190080464A1, 2019.
5. (Active) Ji Hyo Lee, **Kuk Jin Yoon**, and Woo Sup Han, “Object Recognition System using Left and Right Images and Method”, Active, US9984280 B2, 2018.

4. (Active) Ji Ho Chang, Jae Chan Jeong, Ho Chul Shin, Dae Hwan Hwang, Seung Min Choi, Eul Gyoong Lim, Jae IL Cho, and **Kuk Jin Yoon**, “Stereo Matching Method and Device for Performing the Method”, Active, US9967516 B2, 2018.
3. (Active) Young-Su Moon, **Kuk Jin Yoon**, and Jae-hyun Kim, “Method and Apparatus for Estimating Image Optical Flow”, Active, US9811918 B2, 2017.
2. (Active) Sung-Hyun Kim, **Kuk-Jin Yoon**, Seung-Hwan Bae, Yeong-Jun Jo, Tae-Kyung Kim, and Ji-Woon Jung, “Polyp Detection Apparatus and Method of Operating the Same”, Active, US9530205 B2, 2014.
1. (Active) **Kuk-Jin Yoon**, Makoto Kimura, Jin-kyung Lee, Yasuo Takane, Tae-kyung Kim, Hyun-seok Choi, Taek-seong Jeong, Kyoung-hwan Moon, and Takashima Masahiro, “Method for Improving 3-Dimensional Effect and Reducing Visual Fatigue and Apparatus Enabling the Same”, Active, US8760502 B2, 2014.

### Domestic

8. (등록) 조대용, **윤국진**, “객체 검색 후보 영역을 개선하기 위한 방법, 컴퓨터-판독가능 저장 매체 및 장치,” KR 등록번호 10-1874471
7. (등록) **윤국진**, 박민규, “신뢰적도에 따른 레버리지 스테레오 매칭 방법, 장치 및 컴퓨터-판독 가능 저장 매체,” KR 등록번호 1017685330000
6. (등록) 이정균, **윤국진**, “이미지를 이용하는 카메라의 방향과 관련한 정보 추정장치 및 추정 방법,” KR 등록번호 10-1847113
5. (등록) 윤주홍, 황영배, 최병호, 윤국진(**Kuk-Jin Yoon**), “객체 간의 상대 움직임 정보를 이용한 영상 기반 계층적 다중 객체 추적 방법 및 시스템”, KR 등록번호 1017683720000
4. (등록) **윤국진**, 김수아, “3차원 객체 검출 및 자세추정 방법,” KR, 등록번호 10-1819730
3. (등록) **윤국진**, 박민규, “신뢰 기반 재귀적 깊이 영상 필터링 방법,” KR, 등록번호 1017633760000
2. (출원) 배승환, 조영준, 김성현, 김태경, 정지운, **윤국진**, “용종 검출 장치 및 그 동작방법 (Polyp Detection Apparatus and Operating Method for the Same),” KR, 출원 번호 10-2013-0130334
1. (등록) 이지효, **윤국진**, 한우섭 “물체 인식 시스템 및 그 물체 인식 방법 (Object Recognition System and Method the Same),” KR, 등록번호 1017157820000

### Research Projects<sup>1</sup>

58. Development of Quadruped Robot for Surveillance, Reconnaissance, and Search Missions: ADD, 140M KRW (per year) , 12/2019 – 11/2023
57. **(PI)** Automatic Color Texture Generation for 3D Point Cloud Data: KETI, 80M KRW, 06/2019 – 11/2019

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<sup>1</sup>1,100 KRW = 1 US Dollar, 10M KRW  $\approx$  9090 US Dollar

56. **(PI)** Vision-based Abnormal Event Detection: Hyundai Heavy Industries, 50M KRW, 04/2019 – 12/2019
55. **(PI)** AAVM Pedestrian Detection: Hyundai Construction Equipment, 60M KRW, 02/2019 – 12/2019
54. **(PI)** Computer Vision Algorithms based on 360° Cameras and Event Cameras: Naver Labs, 85M KRW, 01/2019 – 01/2020
53. **(PI)** Accurate Stereo Matching Algorithm for Indoor Robot Navigation: Samsung Research, 96M KRW, 05/2018 – 04/2019
52. Research on Multi-modal Hand Control, Korea Ministry of Trade, Industry and Energy (MOTIE), 140M KRW (per year), 04/2018 – 12/2021
51. **(PI)** Research on Event Camera-based Computer Vision Algorithms for Visual Intelligence: National Research Foundation of Korea, Korea Ministry of Science and ICT (MSIT), (중견연구자지원사업), 850M KRW (for four years), 03/2018 – 02/2022
50. Fundamental Study of Vision Algorithms for Comprehensive and Thorough Understanding of Videos: KRF, 235M KRW, 08/2017 – 04/2019
49. 4D Reconstruction of Non-rigid Dynamic Objects for Realistic Services: Giga KOREA Foundation, 500M KRW (among total research fund 7,000M KRW), 04/2017 – 12/2020
48. 360° Stereo Camera-based Dynamic Scene Understanding for Autonomous Driving: Samsung Future Technology Foundation, 500M KRW, 09/2016 – 08/2019
47. **(PI)** AR/VR Platform Development for ADAS Research: GIST, 200M KRW, 05/2017 – 12/2017
46. **(PI)** Stereo-based High Speed and High Accurate Depth Sensing for AR HUD: Samsung Electronics, 90M KRW, 07/2016 – 06/2017
45. **(PI)** Visual Attention Estimation for VR: Samsung Electronics, 290M KRW, 05/2016 – 12/2017
44. Depth Sensing and Depth-based Road Monitoring: Korea Ministry of Trade, Industry and Energy (MOTIE), 110M KRW (per year on average), 03/2016 – 12/2017
43. **(PI)** Real-time Multi-Object Tracking: Hyundai Motors, 72.25M KRW, 12/2015 – 11/2016
42. **(PI)** Road Surface Inspection using Depth Images: Hyundai Mobis, 80M KRW, 09/2015 – 11/2016
41. **(PI)** Development of Local Stereo Matching Logic: KETI, 50M KRW, 09/2015 – 05/2016
40. **(PI)** Illumination and Reflection Estimation based on 3D Shape Analysis: ETRI, 50M KRW, 06/2015 – 01/2016
39. **(PI)** Stereo-vision-based 3D Dynamic Environment Analysis for Autonomous Driving of Smart Cars: National Research Foundation of Korea, Korea Ministry of Science, ICT and Future Planning (MSIP), (미래부 중견연구자지원사업 - 도약), 279M KRW (per year), 05/2015 – 04/2018.

38. Online Monitoring and Extracting Features of Emotional Audience Responses during Cultural Events: Korea Ministry of Culture, Sports and Tourism (MCST), 50M KRW (per year), 04/2015 – 03/2018
37. Deep View – Research on Vision- and Learning-based Scene Understanding and Event Forecasting: Korea Ministry of Science, ICT and Future Planning (MSIP), 45M KRW (per year), 03/2014 – 02/2018.
36. Real-time 3D Scene Modeling with Active Vision Sensors: Human-Centered Interaction for Coexistence Project: Korea Ministry of Science, ICT and Future Planning (MSIP), 50M KRW (per year), 09/2012 – 08/2015
35. **(PI)** Structure-from-motion for Mobile Devices: LG Electronics, 30M KRW, 09/2014 – 12/2014
34. **(PI)** Dynamic Scene Understanding using Stereo Cameras: Hyundai Mobis, 72M KRW, 05/2014 – 12/2014
33. **(PI)** High-Speed Optical Flow Estimation: Samsung Electronics, 70M KRW, 04/2014 – 01/2015
32. **(PI)** High Accuracy Stereo Vision with Pattern Projection: Samsung Electronics, 90M KRW, 11/2013 – 09/2014
31. **(PI)** Dynamic Objects Detection and Path Prediction using Stereo Cameras: LG Electronics, 60M KRW, 04/2013 – 12/2013
30. **(PI)** Automatic Polyp Detection in Endoscopic Images, : Samsung Electronics, 85M KRW, 03/2013 – 12/2013
29. Interactive Performance based on Audience Reaction: Korea Ministry of Culture, Sports and Tourism (MCST), 55M KRW, 08/2012 – 03/2013
28. **(PI)** Stereo with 2x2 Camera Array: LG Electronics, 50M KRW, 08/2012 – 07/2013
27. **(PI)** Stereo Matching Robust to Illumination Changes: ETRI, 50M KRW (per year), 05/2012 – 01/2015
26. **(PI)** Multi-baseline Stereo based SLAM for Dynamic Environments: Korea Ministry of Education, Science and Technology (MEST), (기본연구자지원사업 - 신진), 48M KRW (per year), 05/2012 – 04/2015
25. **(PI)** High-quality Disparity Map Estimation with Motion: Samsung Electronics, 90M KRW, 03/2012 – 02/2013
24. **(PI)** Endoscopic Image Processing - Stitching of Non-overlapping Images and Detecting Polyps in Endoscopic Images: Samsung Electronics, 85M KRW, 04/2012 – 12/2012
23. **(PI)** Fusion of Active Laser Sensor and Camera: KIST, 30M KRW, 08/2011 – 08/2012
22. **(PI)** Sensor-fusion-based User Motion Capture: NHN and National IT Industry Promotion Agency (NIPA), 60M KRW, 11/2011 – 06/2012

21. **(PI)** Research on the 3D Scene Reconstruction and Scene Flow Estimation using Multi-view Image Sequence: Korean Ministry of Education, Science and Technology (MEST), (기본연구자지원사업 - 신진), 50M KRW (per year), 05/2009 – 04/2012
20. Realistic Broadcasting Research Center (ITRC): National IT Industry Promotion Agency (NIPA), 20M KRW (per year), 01/2009 – 12/2011 · 3D Reconstruction with Multi-view Video Sequence
19. **(PI)** High-resolution Depth Map Estimation using a Semi-active Stereo Camera System: Samsung Electronics, 52M KRW, 04/2011 – 11/2011
18. **(PI)** Research on the Terrain Matching Methods for Terrain-aided Navigation (TAN): LIG Nex1 and Agency for Defense Development(ADD), 50M KRW, 06/2010 – 05/2011
17. **(PI)** System Development for Illumination Source Estimation: Viewrun and ETRI, 40M KRW, 09/2010 – 06/2010
16. **(PI)** Development of Automatic Inter-Camera Distance Adjustment Methods: Samsung Electronics, 60M KRW, 03/2010 – 12/2010
15. **(PI)** Research on Texture Synthesis and Specular Reflection Removal: ETRI, 60M KRW, 06/2009 – 01/2010
14. **(PI)** Object Contour Extraction for Robot Grasping: KIST, 25M KRW (per year), 01/2009 – 12/2010
13. Development of Experience Tour Technology based on Mobile Mixed Reality: KIST, 20M KRW, 03/2009 – 02/2010
12. **(PI)** Multi-view Image Stitching: Samsung Advanced Institute of Technology, 30M KRW, 07/2009 – 07/2010
11. **(PI)** Object Recognition with Stereo Cameras: Samsung Electronics, 150M KRW, 02/2009 – 12/2009
10. Flamenco Project: (French) National Agency for Research (ANR), 2007 – 2008
9. Robust Robot Vision Research: MOST National Research Laboratory, June 2003.– May 2006.
8. Vision-based Environments Recognition for Network-based Humanoids: KIST, February 2004.– January 2006.
7. Development of the Real-Time 3D Image Sensor: Samkyung Hitech, October 2001.– November 2003.
6. Vision Guidance System based on Human Binocular Vision Model: BSRC, August 2001.– May 2003.
5. Development of Entertainment Robots: HWRS-ERC, March 1999.– February 2003.
4. Imaging System for 3D Display: KIST, 2002.
3. Vision for Mobile Robot: Samsung Electronics, 2002.

2. Image-based Guidance System for AGV: Hyundai Heavy Industry, 2000.
1. Image/Video Indexing: Samsung Advanced Institute of Technology, 2000.

## Teaching (in English)

- Fall 2019: Special Topics in Mechanical Engineering - Programming for Autonomous System
- Spring 2019: Special Topics in Mechanical Engineering - Visual Intelligence
- Fall 2018: Random Data
- Spring 2018: Special Topics in Mechanical Engineering - Visual Intelligence
- Fall 2017: Computer Vision
- Spring 2017: Signals and Systems
- Fall 2016: Computer Vision
- Spring 2016: Digital Image Processing
- Fall 2015: Computer Vision
- Spring 2015: Signals and Systems
- Fall 2014: Computer Vision
- Spring 2013: Signals and Systems
- Fall 2012: High-level Image Understanding & Processing – Computer Vision
- Spring 2012: Signals and Systems
- Fall 2011: Digital Image Processing
- Spring 2011: High-level Image Understanding & Processing – Computer Vision
- Fall 2010: Digital Image Processing
- Spring 2010: High-level Image Understanding & Processing – Computer Vision
- Fall 2009: Digital Image Processing
- Spring 2009: High-level Image Understanding & Processing
- Fall 2008: Digital Image Processing

## Awards

- 제 31회 영상처리 및 이해에 관한 워크샵 우수논문상 (금상), 2019.
- 제 31회 영상처리 및 이해에 관한 워크샵 우수논문상 (동상), 2019.
- Best Student Paper Award (as an Advisor) : IW-FCV 2018, 2018.
- 제 30회 영상처리 및 이해에 관한 워크샵 우수논문상 (은상), 2018.
- 제 30회 영상처리 및 이해에 관한 워크샵 우수포스터논문상, 2018.
- Silver Prize (as an Advisor) : Samsung HumanTech Paper Award, 2017.
- Best Poster Presentation Award (as an Advisor) : IW-FCV 2017, 2017.
- Outstanding Reviewer, ECCV 2016, 2016.
- 제 28회 영상처리 및 이해에 관한 워크샵 우수논문상, 2016.
- Bronze Prize (as an Advisor) : Samsung HumanTech Paper Award, 2016.
- Silver Prize (as an Advisor) : Samsung HumanTech Paper Award, 2015.
- Participation Prize (as an Advisor) : Samsung HumanTech Paper Award, 2015.
- The 1st Place at the 1st Multi-object Tracking Challenge (MOT Competition sponsored by Daimler)
- 제 9회 한국로봇종합학술대회 우수논문상, 2014.

- 제 26회 신호처리 합동 학술대회 우수논문상, 2014.
- 제 26회 영상처리 및 이해에 관한 워크샵 우수논문상, 2014.
- Silver Prize (as an Advisor) : Samsung HumanTech Paper Award, 2014.
- Bronze Prize (as an Advisor) : Samsung HumanTech Paper Award, 2014.
- Silver Prize (as an Advisor) : Samsung HumanTech Paper Award, 2012.
- Grants to Post-Doctoral Fellows by INRIA, 2006.
- Government Grant to Post-Doctoral Fellows by Korea Research Foundation, 2006.
- Silver Prize: Samsung HumanTech Paper Award, 2006.
  - Kuk-Jin Yoon, “Specularity-Invariant Image Representation and Its Application to Correspondence Search and Reflection Components Separation”
- Top 10% among the Accepted Papers: ICIP, 2005.
  - Kuk-Jin Yoon and Yoo-Jin Choi, “Dichromatic-Based Color Constancy Using Dichromatic Slope and Dichromatic Line Space”
- Bronze Prize: Samsung HumanTech Paper Award, 2005.
  - Kuk-Jin Yoon and Yoo-Jin Choi, “Illuminant Chromaticity Estimation Using Dichromatic Slope and Dichromatic Line Space”
- Research Prize: The Fifth Korean Intelligent Robot Contest, 2003.
  - Development of KASIRI III
- The 3rd Place: Best Poster Award in Photonics Boston, 2001.
  - Kuk-Jin Yoon and In So Kweon, “Color Image Segmentation Considering of Human Sensitivity for Color Pattern Variations”

## Invited Talks and Papers

### International

- (Invited Talk) “Applying Deep Learning to 360° and Event Cameras,” DGIST Global Innovation Festival, Korea, 2019
- (Invited Talk) “Generating Content-aware Perspective Videos from 360° Videos for Comfortable 360° Video Watching,” 24th International Workshop on Frontiers of Computer Vision, Japan, 2018
- (Invited Talk) “Generating Content-aware Perspective Videos from 360° Videos for Comfortable 360° Video Watching,” DGIST Global Innovation Festival, Korea, 2017
- (Invited Talk) “Robust Stereo Matching with Temporal Aggregation and Matching Confidence,” International Conference on Internet of Vehicles, Nadi, Fiji, 2016
- (Invited Talk) “How Much Further Can We Go in Two-frame Stereo?”, Symposium on High Precision Stereo Vision, SIAM IS 2014, Hong Kong, 2014
- (Invited Paper) Peter Sturm, Amaël Delaunoy, Pau Gargallo, Emmanuel Prados, **Kuk-Jin Yoon**, “3D and Appearance Modeling from Images,” 14th Iberoamerican Congress on Pattern Recognition, 2009.

### Domestic

- ICROS-KROS 대전충청:ADAS for Autonomous Driving based on Computer Vision and Machine Learning, December 2019.
- 한국자동차공학회: 강인한 자율주행을 위한 360도 이벤트 카메라 응용 연구, October 2019.



- ADD: 360도 카메라 및 이벤트 카메라를 활용한 딥러닝 기반의 환경 인식 연구, September 2019.
- KAIST 문술미래전략대학원: 미래도시: 자율주행자동차, June 2019.
- 삼성전기: Research on event camera-based computer vision algorithms for visual intelligence, June 2019
- Postech: Applying Deep Learning to 360° and Event Cameras, April 2019.
- 연세대학교: DNNs for 360° and Event Cameras, January 2019.
- KCCV 2018 (invited): Joint Layout Estimation and Global Multi-view Registration for Indoor Reconstruction, July 2018.
- ETRI: Multi-camera Network Topology Estimation and Person Re-ID, May 2018.
- GIST: 컴퓨터 비전 및 기계학습 기반 자율주행을 위한 요소 기술, April 2018.
- KIST: 360° Videos and ADAS, April, 2018.
- 네이버랩스(Naver Labs): Survey on Lane-Level Localization, July 2017.
- Vivozon: Computer Vision-based Scene Understanding, September 2017.
- 개방형컴퓨터통신연구회(OSIA): 자율 주행을 위한 컴퓨터 비전 및 머신 러닝 기반 주행 환경 인식 기술, June 2017.
- KCCV 2017 (invited): Multi-attributed Graph Matching with Multi-layer Random Walks, June 2017.
- 네이버랩스(Naver Labs): 영상에서의 Appearance 및 움직임 정보 모델링을 통한 다중 객체 추적, March 2017.
- 경희대학교: 자율주행 자동차를 위한 비전 기반 ADAS 연구, November 2016.
- 자동차 융합 얼라이언스 기술 발전 세미나: 자율주행을 위한 컴퓨터 비전 기반 동적 주행 환경 인식 기술, October 2016.
- KCCV 2016 (invited): Tracking and Identifying Multiple Objects across Multiple Cameras, July 2016.
- 대한전자공학회 영상처리연구회 워크샵: Dynamic 환경에서의 자율 주행체를 위한 비전 기반 응용 기술, July 2016.
- 스마트카 센서/부품 테크포럼 세미나 2016: 컴퓨터 비전 기반 동적 주행 환경 인지 기술, June 2016.
- UMV 자율주행기술 전문가 세미나: 자율 이동체를 위한 영상 기반 상황 센싱 및 인지 기술, June 2016.
- 한국미래기술교육연구원 인공지능 및 카메라/영상인식 기반의 자율 주행차 최신 개발기술 및 센서 적용방안 세미나: 스마트카의 자율주행을 위한 스테레오 영상 기반 동적 상황 인지 기술 연구, April 2016.
- 호남 ETRI, March 2016.
- 대한전자공학회 컴퓨터비전 튜토리얼, February 2016.
- ETRI, Daejeon, December 2015.
- Hyundai Mobis 기술포럼 전문가 세미나: 차량용 카메라 보정을 위한 자세 추정 기법 및 주변 방해물 검출을 위한 3차원 복원 방법, November 2015.
- ETRI: Multiple Object Tracking, Daejeon, September 2015.
- KAIST NOVIC Seminar: 스마트카의 자율주행을 위한 컴퓨터 비전 기반 동적 상황 인지 기술, September 2015.
- KCCV 2015 (invited): Leveraging Stereo Matching with Learning-based Confidence Measures, August 2015.
- POSTECH: Multi-object Tracking Tutorial, August 2015.
- KAIST: 스마트카의 자율주행을 위한 스테레오 영상 기반 ADAS 기술, August 2015.
- 정보과학회 CVPR 워크샵: 스마트카의 자율 주행을 위한 동적 상황 인지 기술, July 2015.
- IPIU 2015 초청논문: 카메라 움직임에 강건한 영상기반 다중객체 추적 방법, February 2015.
- 한국에너지기술연구원: Fourier and Wavelet Transform, January 2015.
- SK Telecom: Robust Online Object Tracking, December 2014.
- SNU: Multi-object Tracking Tutorial, November 2014.

- 자동차 공학회 전기전자ITS 부문 워크샵: Vision-based Moving Obstacle Avoidance for Autonomous Vehicles, October 2014.
- KCCV 2014 (invited): Online Robust Multi-target Tracking, August 2014.
- 정보과학회 여름학교: Geometric Computer Vision, August 2014.
- KETI: Recent Advances on Online Robust Multi-target Tracking, August 2014.
- Hanyang Univ.: Stereo, April 2014.
- POSTECH, Pohang, (Department Seminar) 2014
- Yonsei University, Seoul, January, 2014
- KIST, Seoul, September, 2013
- KIST, Seoul, July 2013
- KETI, Bundang, May 2013
- POSTECH, Pohang , March 2013
- Inha Univ., Incheon , January 2013
- KICT, Goyang-si, December 2012
- Dongseo Univ., Busan, November 2012
- ETRI, Daejeon, May 2012
  - Title: Semi-active Stereo Vision
- Korean Society of Broadcast Engineers, Seoul, August 2011
  - Title: Tutorial on Stereo Vision
- Pentech, Seoul, July 2011
  - Title: Computer Vision for Mobile Devices
- GIST Science School, Gwangju, November 2010
- Yeungnam University, Kyungsan, November 2010
- Agency for Defense Development(ADD), Daejeon, July 2010
  - Title: Tracking Filters for Terrain-Aided Navigation
- Samsung Electronics, Suwon, May 2010.
  - Title: Introduction to Stereo Vision and 3D Reconstruction
- LIG NEX1, Suwon, April 2010
  - Title: Terrain-Aided Navigation
- Electronics and Telecommunications Research Institute (ETRI), Daejeon, Korea, April 2010.
- Electronics and Telecommunications Research Institute (ETRI), Daejeon, Korea, July 2009.
- Daegu Gyeongbuk Institute of Science and Technology (DGIST), Daegu, Korea, December 2008.
- Korea Institute of Science and Technology (KIST), Seoul, Korea, December 2008.
- Department of Electrical Engineering and Computer Science, KAIST, Daejeon, Korea, October 2008.
  - Title: Stereo Vision
- Department of Information and Communications, GIST, Gwangju, Korea, February 2008.
  - Title: Multi-view Stereo under Image Ambiguity and Appearance Changes
- Perception Team in INRIA Rhône-Alpes, Montbonnot, France, September 2006.
  - Title: Stereo Matching under Image Ambiguity and Appearance Changes
- The 4th KAIST-Tsinghua Joint Workshop on Pattern Recognition, Daejeon, Korea, September 2005.
  - Title: Reflection Analysis using a Single Color image and Its Application to Stereo
- The 1st International Joint Workshop of KAIST-RCV and U.Tokyo-Ikeuchi Lab. on Robust Vision Tech-

- nology, Daejeon, Korea, April 2005.
  - Title: Robust Vision Techniques based on the Local-Level Analysis of Image Information
- The 3th KAIST–Tsinghua Joint Workshop on Pattern Recognition, Beijing, China, December 2004.
  - Title: Locally Adaptive Support-Weight Approach for Visual Correspondence Search
- Samsung Advanced Institute of Technology, December 2003.
  - Title: Stereo Vision
- NRL(National Research Laboratory) Joint Workshop on Intelligent Robot Technology, Kyungju, Korea, October 2003.
  - Title: 3D Computation, Obstacle Detection/Avoidance, and Object Tracking using Stereo Vision for Intelligent Robots
- The 6th Autumn Seminar of a Korean Society for the 3D Medical Image Research, September 2001.
  - Title: Tutorial on the 3D Modeling from Multiple Images
- Advanced Science Institute 2001, Tokyo, Japan, July 2001.
  - Title: Computer Vision Applications

## **Academic and Campus Responsibilities**

- Editor of the International Journal of Automotive Technology (IJAT)
- Area Chair of CVPR 2020, ICCV 2019, ACM MULTIMEDIA 2019
- Reviewer of CVPR, ICCV, ECCV, ACCV, International Journal of Computer Vision (IJCV), IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI), IEEE Transactions on Image Processing(TIP), Computer Vision and Image Understanding(CVIU), Pattern Recognition(PR), etc.
- Program Committee in CPCV, KCCV
- Secretary-Treasurer of GIST Faculty Assembly (2016 – 2017)